BTH-1208LS

Wireless Multifunction DAQ Device

User's Guide

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About this User's Guide

What you will learn from this user's guide

This user's guide describes the Measurement Computing BTH-1208LS wireless data acquisition device and lists device specifications.

Conventions in this user's guide

For more information

Text presented in a box signifies additional information and helpful hints related to the subject matter you are reading.

Caution!	Shaded caution statements present information to help you avoid injuring yourself and others, damaging your hardware, or losing your data.
bold text	Bold text is used for the names of objects on a screen, such as buttons, text boxes, and check boxes.
italic text	Italic text is used for the names of manuals and help topic titles, and to emphasize a word or phrase.

Where to find more information

Additional information about the BTH-1208LS is available on our website at www.mccdaq.com. You can also contact Measurement Computing Corporation by phone, fax, or email with specific questions.

- Knowledgebase: <u>kb.mccdaq.com</u>
- Phone: 508-946-5100 and follow the instructions for reaching Tech Support
- Fax: 508-946-9500 to the attention of Tech Support
- Email: techsupport@mccdaq.com

Introducing the BTH-1208LS

The BTH-1208LS is a multifunction data acquisition device that communicates using Bluetooth® wireless technology.

The device is supported under the following operating systems:

- Microsoft® Windows® 8/7/Vista® (SP2)/XP (SP3) (32-bit or 64-bit)
- AndroidTM 3.1 or later

The Bluetooth radio host used with the device must support Bluetooth 2.0 or later. The following Bluetooth stack protocols are supported on Windows:

- Microsoft Bluetooth stack
- Broadcom ® Bluetooth stack (not supported by Windows XP SP3)

The device supports USB 2.0 full-speed when connected to a USB port. The device is also compatible with USB 1.1 ports; however, the speed of the device may be limited when using a USB 1.1 port due to the difference in transfer rates on USB 1.1 versions of the protocol (low-speed and full-speed).

Device features

The BTH-1208LS provides the following features:

- Eight 11-bit single-ended (SE) or four 12-bit differential (DIFF) analog input channels
- 1 kS/s max sampling rate in Bluetooth continuous scan mode
- 50 kS/s sampling rate in Bluetooth burst I/O mode and when communicating over USB connection
- Software-selectable analog input ranges of ±10 V (SE), and ±20 V, ±10 V, ±5 V, ±4 V, ±2.5 V, ±2.0 V, ±1.25 V, and ±1.0 V (DIFF).
- Two 12-bit analog outputs
- Eight individually-configurable digital I/O channels
- One 32-bit event counter
- One external digital trigger input
- One external clock input
- Two screw terminal connectors for field wirings
- Powered by two AA batteries (standard or rechargeable) when in Bluetooth mode; can also be powered by a USB power supply in Bluetooth mode or from the USB host in USB mode

Functional block diagram

BTH-1208LS functions are illustrated in the block diagram shown here.

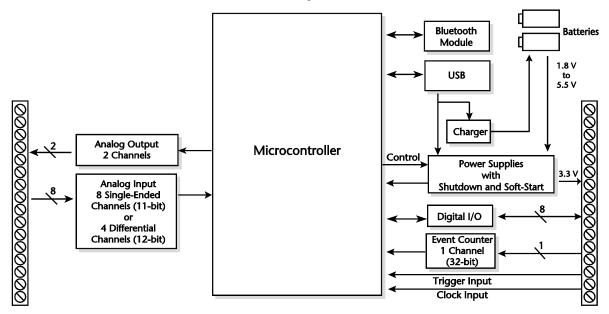


Figure 1. Functional block diagram

Installing a BTH-1208LS

What comes with your shipment?

Verify that the following hardware components are included in the shipment:

Hardware

- BTH-1208LS
- USB cable
- Two rechargeable AA NiMh batteries

Software

MCC DAQ CD

Documentation

■ MCC DAQ Software Quick Start Guide

The Quick Start Guide booklet provides an overview of the MCC DAQ software you received with the device, and includes information about installing the software. Please read this booklet completely before installing any software or hardware.

■ BTH-1208LS Quick Start

Unpacking

As with any electronic device, take care while handling to avoid damage from static electricity. Before removing the BTH-1208LS from its packaging, ground yourself using a wrist strap or touch either the computer chassis or other grounded object to eliminate any stored static charge.

If the device is damaged, notify Measurement Computing Corporation immediately.

Installing the software

Installing in a Windows environment

Refer to the *Quick Start Guide* that ships with your device for instructions on installing the MCC DAQ software in a Windows environment. This booklet is available in PDF at www.mccdaq.com/PDFmanuals/DAQ-Software-Quick-Start.pdf.

Running and deploying apps in an Android environment

For instructions on deploying and running apps in an Android environment, refer to the *UL for Android Example Projects* topic in the *Universal Library for Android Help* that installs with the UL for Android software library on the MCC DAQ CD.

Pairing with the host device

Pairing creates a bond between a Bluetooth device and a *host device*. A host device can be either a Windowsbased computer or an Android device (tablet, phone, or mini-PC).

The BTH-1208LS must be paired with the host device before it can establish a wireless connection and transmit acquired data to the device. A BTH-1208LS only has to be paired once with a particular host device.

The BTH-1208LS can be paired or connected when powered by:

- batteries (standard or rechargeable)
- an external USB power supply

The BTH-1208LS *cannot* be paired when powered by a USB host device.

To pair the BTH-1208LS as a Bluetooth device, make sure the device is not connected to a USB host, and complete the following steps (refer to Figure 2 on page 12 for the location of device components referenced in this section):

- 1. Make sure the host device is configured to host a Bluetooth device. Refer to host device documentation to learn how to enable Bluetooth and how to search for and pair with Bluetooth devices.
- 2. If powered by batteries, press and hold the button for at least five seconds to power on the device and put it into pairing mode.
 - If powered by a USB power supply, press and hold the button for at least three seconds to put it into pairing mode.
 - When the **Power** and **Status** LEDs blink alternately, the device is in pairing mode and is ready to pair with the host device.
- 3. Select the Bluetooth device setup in the host device OS software, and then select the BTH-1208LS when it displays. Refer to the Bluetooth documentation of your host device to learn how to pair it with a Bluetooth device.
 - For example, in Windows, select **Bluetooth Device** from the Control Panel, and then double-click on **BTH-1208LS-xxxx** in the **Add a device** dialog box (**xxxx** are the last four digits of the device serial number. You may need to wait a few seconds for the device to display.
- 4. If host device requests a passkey, PIN or pairing code, enter the default value for the device (0000).
- 5. Press and hold the power/pairing button for two seconds to remove the device from pairing mode.

Once the BTH-1208LS is paired to the host device, run an application that communicates with the device (such as InstaCal) to establish a connection. The **Status** LED turns on to indicate a Bluetooth connection is established.

Note 1: Measurement Computing recommends that you connect one of the digital grounds (**GND**) to earth ground to reduce the chance of the BTH-1208LS unexpectedly powering down due to electrostatic discharge.

Installing the hardware in USB mode (Windows only)

The driver needed to run the BTH-1208LS device is installed when you install the software. Therefore, you need to install the software package you plan to use before you install the hardware. For operation on a Windows operating system, Measurement Computing recommends that you run Windows Update to update your operating system with the latest USB drivers.

Connect the USB cable to an available USB port on the computer or to an external USB hub connected to the computer. Connect the other end of the USB cable to the USB connector on the device. No external power is required.

Configuring Bluetooth settings

All Bluetooth settings except for the pairing code can be changed when the BTH-1208LS is either physically or wirelessly connected to the host device. The pairing code can only be changed when the BTH-1208LS is physically connected to the host device.

You can configure the following Bluetooth settings on the BTH-1208LS through software. For example, if you are using the device in a Windows environment, you can configure these settings with InstaCal.

■ **Pairing code** – Four digit code that identifies the BTH-1208LS to the host device (default = 0000). The pairing code cannot be changed when the BTH-1208LS is connected wirelessly to the host device.

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■ Bluetooth connection status notifications – You can set values that indicate when the device is connected over Bluetooth, and when the Bluetooth connection terminates. Connected and disconnected values can be set for digital outputs, analog output channel 0, and analog input channel 1

- **Auto shutdown** When the device is powered by batteries, you can configure the device to power down a specified amount of time after the Bluetooth connection terminates.
- **Battery charging** When the device is powered by rechargeable batteries, you can configure the device to recharge batteries from the USB power supply when connected over Bluetooth.

Calibrating the hardware

Factory calibration

The Measurement Computing Manufacturing Test department performs the initial factory calibration. Return the device to Measurement Computing Corporation when calibration is required. The recommended calibration interval is one year.

Field calibration

Field calibration is not supported.

Functional Details

Analog input acquisition modes

The BTH-1208LS can acquire analog input data in three different modes – software paced, continuous scan, and burst scan.

Software paced mode

In software paced mode you can acquire one analog sample at a time. You initiate the A/D conversion by calling a software command. The analog value is converted to digital and returned to the computer. You repeat this procedure until you have the total number of samples that you want from one channel.

- When communicating over a Bluetooth connection, the typical throughput sample rate in software paced mode is 10 S/s (system-dependent).
- When communicating over a USB connection, the typical throughput sample rate in software paced mode is 250 S/s (system-dependent).

Continuous scan mode

In continuous scan mode you can acquire data from up to eight channels. The analog data is continuously acquired and converted to digital values until you stop the scan.

When communicating over a Bluetooth connection, the maximum continuous scan rate of 1024 S/s is an aggregate rate. The total acquisition rate for all channels cannot exceed 1024 S/s. The following table lists the scan rates when scanning from one to eight channels in Bluetooth mode.

N 4				·	M 4 4I-	1 -
ıvıaxımum	continuous	scan	rate i	ın E	siuetootn	mode

# channels scanned	Scan rate (S/s)
1	1024
2	512
3	341.33
4	256
5	204.8
6	170.67
7	146.28
8	128

When communicating over a USB connection, the maximum continuous scan rate of 50 kS/s is an aggregate rate. The total acquisition rate for all channels cannot exceed 50 kS/s. Data is transferred in blocks of 32 samples from the device to the memory buffer on your computer.

The following table lists the scan rates when scanning from one to eight channels in USB mode.

Maximum continuous scan rate in USB mode

# channels scanned	Scan rate (kS/s)
1	50
2	25
3	16.70
4	12.50
5	10
6	8.30
7	7.14
8	6.25

In both Bluetooth mode and USB mode, you can start a hardware paced continuous scan with either a software command or with an external hardware trigger event.

Burst scan

In burst scan mode (BURSTIO) you can acquire data at the maximum throughput of 50 kS/s from the BTH-1208LS when connected in Bluetooth mode. BURSTIO doesn't offer any advantage in USB mode, since these rates are supported for BLOCKIO in USB mode.

Sample sizes are limited to the size of the FIFO (12288 samples) in BURSTIO mode. The acquired data is read from the FIFO and transferred to a user buffer in the computer. You can initiate a single acquisition sequence of one to eight channels with either a software command or an external hardware trigger event.

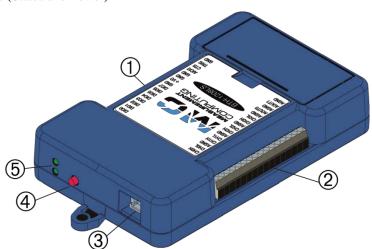
Burst scans are limited to the depth of the on-board memory, as the data is acquired at a rate faster than it can be transferred to the computer. Keep in mind that when using Bluetooth, the rate of transfer of the acquired data to the host is still limited, so the process can take several seconds. Time must be allowed between scans for the acquisition AND the transfer of the data.

The maximum sampling rate is an aggregate rate. The total sample rate using burst scan mode is 50 kS/s per channel for any or all channels. An error occurs if you exceed the FIFO capacity and acquire more than 12,288 samples in BURSTIO mode.

BTH-1208LS components

These BTH-1208LS components are shown in Figure 2.

- Screw terminal connectors
- USB connector
- Power/pairing button
- LED indicators (Status and Power)



- Screw terminals for digital I/O, digital trigger, power out, clock input, and counter input
- 2 Screw terminals for analog input and analog output
- 3 USB connector

- Power/pairing button
- Power LED (top) and Status LED (bottom)

Figure 2. Components

USB connector

The USB connector provides 5 V power when connected to a USB power supply, and provides both power and communication when the device is connected to a USB port. If rechargeable NiMH or NiCd batteries are installed, batteries recharge when the device is connected to a USB host or power supply.

Power/pairing button

The power/pairing button has different functions depending on the power source of the device.

The term *pairing* refers to one function of the button – to put the device in *pairing mode* so it can establish an association between the Bluetooth radio on the host device and the BTH-1208LS radio.

Button functions are listed in the table below.

Power/pairing button functions

Power Status	Button Functions
Battery powered	 To power on the device, press and hold the button for 3 seconds. To enter pairing mode, hold the button for an additional 2 seconds. To remove the device from pairing mode, press and hold the button again for 2 seconds. To power off the device when not in pairing mode, press and hold the button for 2 seconds
Powered by USB charger/USB power supply	 To put the device in pairing mode when it is powered on, press and hold button for 2 seconds. To remove the device from pairing mode, press and hold the button again for 2 seconds.
Powered by USB host port or hub	The power/pairing button is disabled.

LEDs

The Power LED indicates the power status of the device. The Status LED indicates the communication status of the device.

LEDs cannot be disabled. LED states are listed in the tables below.

Power and Status LED behavior

Power LED	Indication
Steady green	The device is powered by USB and the batteries are sufficiently charged or not installed.
Blinks continuously	 If the device is connected to USB port/host, then the batteries are recharging (only if rechargeable batteries are installed). If the device is not connected to USB port, then it is powered by batteries. If the Power LED is blinking alternately with the Status LED, then the device is in pairing mode.
Off	Device is off.
Status LED	Indication
Steady green	Bluetooth or USB connection established
Blinks continuously	 Communication with host computer occurring over Bluetooth or USB connection. If the Status LED is blinking alternatively with the Power LED, then device is in pairing mode.
Off	A Bluetooth or USB connection is not established

Screw terminals

The screw terminals provide the followings:

- Eight analog inputs (CH0H/CH0L to CH3H/CH3L)
- Two analog outputs (AOUT0 and AOUT1)
- Eight digital I/Os (**DIO0** to **DIO7**)
- One external trigger input (**TRIG**)
- One external counter input (CTR)
- One external clock input (AICKI)
- One power output (**+VO**)
- Six analog grounds (**AGND**)
- Four digital grounds (**GND**)

Use 16 AWG to 30 AWG wire when makings to the screw terminals.

The single-ended mode pinout is shown in Figure 3.

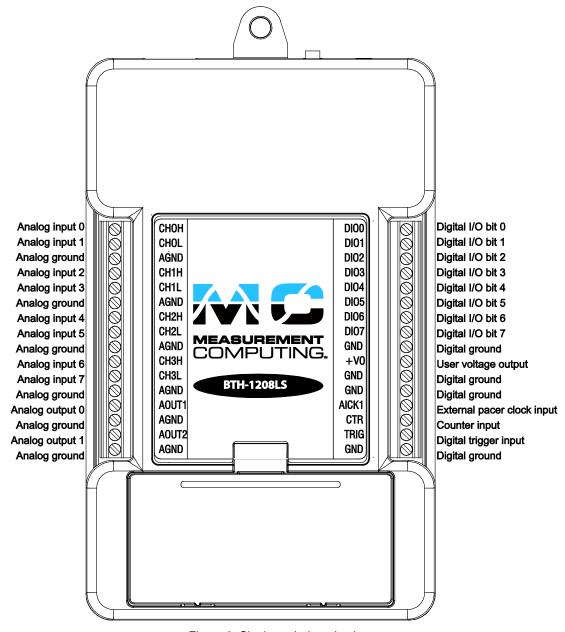


Figure 3. Single-ended mode pinout Distributed By MicroDAQ, LLC 603-746-5524

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The differential mode pinout is shown in Figure 4.

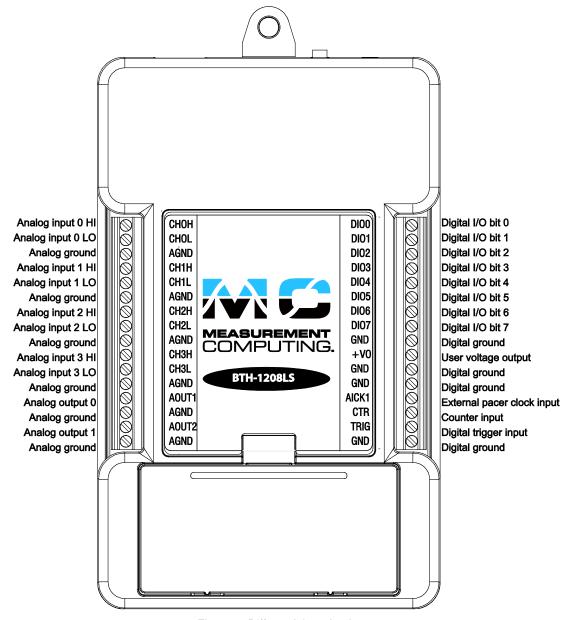


Figure 4. Differential mode pinout

Signals

Analog input

You can connect up to eight single-ended analog inputs (CH0 to CH7) or four differentials (CH0H/CH0L to CH3H/CH3L).

Single-ended configuration

When configured for single-ended input mode, eight analog input channels are available. Each analog input has 11-bit resolution (due to restrictions imposed by the A/D converter) and offers a ± 10 V analog input range.

The input signal is referenced to signal ground (AGND), and is delivered through two wires:

- Connect the wire carrying the signal to be measured to CHx.
- Connect the second wire to AGND Distributed By MicroDAQ, LLC 603-746-5524 www.MicroDAQ.com

Single-ended measurements using differential channels

To perform a single-ended measurement using differential channels, connect the signal to the **CHxH** input, and ground the associated **CHxL** input.

Differential configuration

When the analog input channels are configured for differential input mode, four analog input channels are available. A low-noise precision programmable gain amplifier (PGA) is available on differential channels. Each analog input has 12-bit resolution and offers software-selectable analog input ranges of ± 20 V, ± 10 V, ± 5 V, ± 4 V, ± 2.5 V, ± 2.0 V, ± 1.25 V, and ± 1.0 V.

In differential mode, the input signal is measured with respect to the low input, and is delivered through three wires:

- Connect the wire carrying the signal to be measured to **CHxH**.
- Connect the wire carrying the reference signal to **CHxL**.
- Connect the third wire to AGND.

In differential mode, the following two requirements must be met for linear operation:

- Any analog input must remain in the −10 V to 20 V range with respect to ground at all times.
- The maximum differential voltage on any analog input pair must remain within the selected voltage range.

Channel gain queue

The channel gain queue feature allows you to set up a scan sequence with a unique per-channel gain setting and channel sequence. The gain settings are stored in a channel-gain queue list that is written to local memory on the device.

The channel-gain queue list can contain up to up to 8 elements in single-ended mode or four elements in differential mode. The elements must be unique and listed in ascending order. An example of a three-element list is shown in the table below.

Element	Channel	Range
0	CH0	BIP10V
1	CH2	BIP5V
2	CH3	RIP10V

Sample channel gain queue list

When a scan begins with the gain queue enabled, the BTH-1208LS reads the first element, sets the appropriate channel number and range, and then acquires a sample. The properties of the next element are then retrieved, and another sample is acquired. This sequence continues until all elements in the gain queue have been selected. When the end of the channel list is detected, the sequence returns to the first element in the list. This sequence repeats until the specified number of samples is acquired.

Carefully match the gain to the expected voltage range on the associated channel or an over range condition may occur. Although this condition does not damage the device, it does produce a useless full-scale reading, and can introduce a long recovery time due to saturation of the input channel.

Analog output

Two 12-bit analog outputs are available at **AOUT0** and **AOUT1**.

Each analog output channel has an output range of 0 V to 2.5 V. Throughput is system-dependent. The D/A is software paced.

External clock input

Connect an external clock signal to **AICKI** to pace input scanning operations.

Digital I/O

You can connect up to eight digital I/O lines to **DIO0** through **DIO7**. When configured for input, the digital terminals can detect the state of any TTL-level input.

Digital input voltage ranges of up to 0 to 5.5 V are permitted, with thresholds of 0.8 V (low) and 2.0 V (high).

Each DIO channel is an *open-drain*, which can sink up to 50 mA for direct drive applications when used as an output.

Figure 5 shows an example of a typical digital output connection.

Typical DIO channel

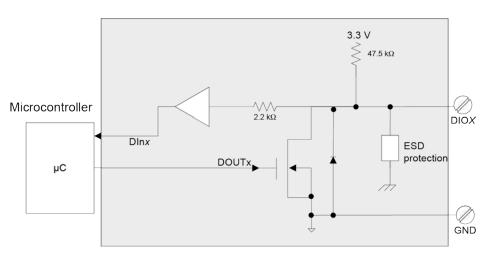


Figure 5. Digital output connection (typical)

External pull-up capability

Inputs are pulled high by default to 3.3 V through 47.5 k Ω resistors on the circuit board. The pull-up voltage is common to all 47.5 k Ω resistors.

You can place an external pull-up resistor on any of the DIO bits in order to limit source current to less than 50 mA., which requires a 100 Ω resistor minimum. A 2 k Ω or 5 k Ω resistor would be typically used, allowing for a 1 mA current

You can also use an external pull-up resistor to pull the DIO bit up to a voltage that exceeds the internal 3.3 V pull-up voltage (5.5 V maximum).

When using external pull-up resistors, be aware that the internal resistors cause a slight voltage shift to digital lines in the on state as various lines change between the on/off states.

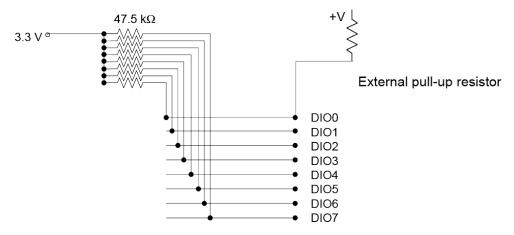


Figure 6. Digital I/O external resistor configuration

Trigger input

The **TRIG_IN** pin is an external digital trigger input that you can configure for either rising/falling edge, or high/low level.

Counter input

The CTR pin is a 32-bit event counter that can accept frequency inputs up to 1 MHz. The internal counter increments when the TTL levels transition from low to high.

Ground

The analog ground (**AGND**) pin provide a common ground for all analog channels. The digital ground (**GND**) pins provide a common ground for the digital, trigger, counter, and power terminals.

Power output

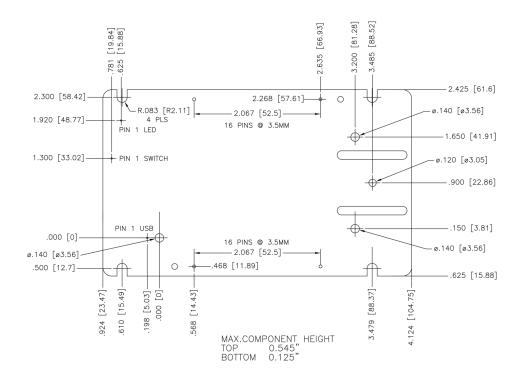
The +**VO** pin is a 3.3 volt output that can source up to 50mA that is supplied by the power source of the device. You can use this terminal to power external devices or circuitry.

Caution! The **+V0** pin is an output. Do not connect to an external power supply or you may damage the BTH-1208LS and possibly the computer.

For more information about signals

For more information about analog and digital signals, refer to the *Guide to DAQ Signal Connections* at www.mccdaq.com/pdfs/DAQ-Signal-Connections.pdf.

Mechanical drawings



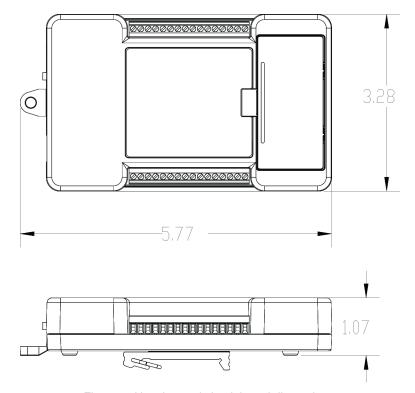


Figure 7. Housing and circuit board dimensions

Specifications

All specifications are subject to change without notice. Typical for 25°C unless otherwise specified. Specifications in *italic text* are guaranteed by design.

Analog input

Table 1. Analog input specifications

Parameter	Condition	Specification
A/D converter type		Successive approximation type
Input voltage range for linear operation	CHx to GND	Single-ended mode: ±10 V max
		Differential mode: -10 V min, 20 V max
Absolute maximum input voltage	CHx to GND	±25 V max
Input impedance		$140 k\Omega$
Input current (Note 1)	$V_{in} = +10 \text{ V}$	70 μA typ
	$V_{in} = 0 V$	-12 μA typ
	$V_{in} = -10 \text{ V}$	–94 μA typ
Number of channels		8 single-ended or 4 differential; software-selectable
Input ranges	Single-ended	±10 V, G=2
	Differential	±20 V, G=1
		±10 V, G=2
		±5 V, G=4
		±4 V, G=5
		±2.5 V, G=8
		±2.0 V, G=10
		±1.25 V, G=16
		±1.0 V, G=20
		Software-selectable
Throughput (Note 2)	Software paced	10 S/s typ, system-dependent (Bluetooth)
		250 S/s typ, system-dependent (USB)
	Continuous scan	0.014 S/s to 1024 S/s (Bluetooth)
		0.014 S/s to 50 kS/s (USB)
	Burst	0.014 S/s to 50 kS/s to 12K (12,288) sample FIFO
		Transfer rate to host is limited to 1024 S/s
		(Bluetooth)
Channel gain queue		Software selectable. 8 elements in SE mode,
		4 elements in DIFF mode.
		One gain element per channel. Elements must be
		unique and listed in ascending order.
Resolution (Note 3)	Differential	12 bits, no missing codes
	Single-ended	11 bits
Integral linearity error		±1 LSB typ
Differential linearity error		±0.5 LSB typ
Repeatability		±1 LSB typ
Trigger source	Software-selectable	External digital: TRIG_IN
		Software-selectable
Pacer source	Software-selectable	■ Internal
		■ External (AICKI), rising edge triggered
		Software-selectable

Note 2: Input current is a function of applied voltage on the analog input channels. For a given input voltage, V_{in} , the input leakage is approximately equal to $(8.181 * V_{in} - 12) \mu A$.

Note 3: Maximum throughput when scanning is machine dependent.

Note 4: The AD7870 converter only returns 11 bits (0 to 2,047 codes) in single-ended mode.

Accuracy

Table 2. Accuracy, differential mode

Range	Accuracy (LSB)
±20 V	5.1
±10 V	6.1
±5 V	8.1
±4 V	9.1
±2.5 V	12.1
±2 V	14.1
±1.25 V	20.1
±1 V	24.1

Table 3. Accuracy, single-ended mode

Range	Accuracy (LSB)
±10 V	4.0

Table 4. Accuracy components, differential mode – all values are (±)

Range	% of Reading	Gain Error at FS (mV)	Offset (mV)	Accuracy at FS (mV)
±20 V	0.2	40	9.766	49.766
±10 V	0.2	20	9.766	29.766
±5 V	0.2	10	9.766	19.766
±4 V	0.2	8	9.766	17.766
±2.5 V	0.2	5	9.766	14.766
±2 V	0.2	4	9.766	13.766
±1.25 V	0.2	2.5	9.766	12.266
±1 V	0.2	2	9.766	11.766

Table 5. Accuracy components, single-ended mode – all values are (±)

Range	% of Reading	Gain Error at FS (mV)	Offset (mV)	Accuracy at FS (mV)
±10 V	0.2	20	19.531	39.531

Noise performance

Table 6. Noise performance, differential mode

Range	Typical counts	LSB _{rms}
±20 V	3	0.45
±10 V	3	0.45
±5 V	3	0.45
±4 V	4	0.61
±2.5 V	5	0.76
±2 V	7	1.06
±1.25 V	10	1.52
±1 V	12	1.82

Table 7. Noise performance, single-ended mode

Range	Typical counts	LSB _{rms}
±10 V	6	0.91

Analog output

Table 8. Analog output specifications

Parameter	Condition	Specification
Resolution		12-bits, 1 in 4,096
Output range		0 V to 2.5 V
Number of channels		2
Throughput (Note 4)	Software paced	10 S/s single channel typ, PC dependent
Power on and reset voltage	USB operation	Initializes to 000h code
	Bluetooth operation	The outputs can be individually configured to initialize to 000h or to have user configurable values written to the outputs when the Bluetooth host is connected or disconnected.
Output current drive	Each D/A OUT	5 mA source capability
Slew rate		0.75 V/ μs typ

Table 9. Analog output accuracy, all values are (±) accuracy tested at no load

Range	Accuracy (LSB)
0 V to 2.5 V	8.0 typ, 73.0 max

Table 10. Analog output accuracy components, all values are (±)

Range	% of FSR	Gain Error at FS (mV)	Offset (mV)	Accuracy at FS (mV)
0 V to 2.5 V	0.16 typ,1.44 max	4.0 typ, 36.0 max	1.0 typ, 9.0 max (Note 4)	5.0 typ, 45.0 max

Note 5: Zero-scale offsets may result in a fixed zero-scale error producing a *dead-band* digital input code region. In this case, changes in digital input code at values less than 0x040 may not produce a corresponding change in the output voltage. The offset error is tested and specified at code 0x040.

Digital input/output

Table 11. Digital I/O specifications

Parameter	Specification
Digital type	3.3 V open drain
Output value mapping	0 written: output drives to DGND
	1 written: output is pulled up to 3.3 V via internal resistor
Number of I/O	8
Configuration	Individually configurable
Input voltage range	0 V to 5.5 V (Note 6)
Pull up/pull-down configuration	47.5 kΩ pull-up resistors (to 3.3 V), 2.2 kΩ series resistors
Input high voltage threshold	2.0 V min
Input high voltage limit	5.5 V absolute max
Input low voltage threshold	0.8 V max

Input low voltage limit	−0.5 V absolute min
	0 V recommended min
Output voltage range	0 V to 3.3 V (no external pull up resistor)
	0 V to 5.5 V max (Note 6)
Output off state leakage current	1.0 μA typ. (Note 7)
Sink current capability	50 mA max (continuous) per pin
Transistor on resistance	0.7 Ω max
Power on and reset state	USB operation: All input
	Bluetooth operation: The digital I/O can either be all input at power on / reset or may
	be configured to have user-configurable patterns written to the DIO when the
	Bluetooth host is connected or disconnected.

- **Note 6:** Each transistor source pin is internally connected to DGND.
- Note 7: The external pull-up is connected to the digital output bit through an external pull-up resistor. Adding an external pull-up resistor connects it in parallel with the internal 47.5 k Ω pull-up resistor of that particular digital input/output bit. Careful consideration should be made when considering the external pull-up resistor value and the resultant pull-up voltage produced at the load.
- **Note 8:** Does not include the additional leakage current contribution through the internal or any external pull-up resistor.

External trigger

Table 12. Digital trigger specifications

Parameter	Specification	
Trigger source (Note 7)	External digital; TRIG_IN terminal	
Trigger mode	Software configurable for edge or level sensitive, rising or falling edge, high or low level.	
Trigger latency	10 μs max	
Trigger pulse width	1 μs min	
Input type	Schmitt trigger, 47 kΩ pull-down to ground	
Schmitt trigger hysteresis	0.76 V typ	
	0.4 V min	
	1.2 V max	
Input high voltage threshold	1.74 V typ	
	1.3 V min	
	2.2 V max	
Input high voltage limit	5.5 V absolute max	
Input low voltage threshold	0.98 V typ	
	0.6 V min	
	1.5 V max	
Input low voltage limit	−0.5 V absolute min	
	0 V recommended min	

External clock input

Table 13. External clock input specifications

Parameter	Specification
Terminal name	AICKI
Terminal type	Input
Input clock rate	50 kHz, max
Clock pulse width	1 μs min
Input type	Schmitt trigger, 47 kΩ pull-down to ground

Schmitt trigger hysteresis	0.76 V typ
	0.4 V min
	1.2 V max
Input high voltage threshold	1.74 V typ
	1.3 V min
	2.2 V max
Input high voltage limit	5.5 V absolute max
Input low voltage threshold	0.98 V typ
	0.6 V min
	1.5 V max
Input low voltage limit	−0.5 V absolute min
	0 V recommended min

Counter

Table 14. Counter specifications

Parameter	Specification			
Pin name	CTR			
Counter type	Event counter			
Number of channels	1			
Input type	Schmitt trigger, 47 kΩ pull-down to ground, rising edge triggered			
Input source	CTR screw terminal			
Resolution	32 bits			
Maximum input frequency	1 MHz			
High pulse width	500 ns min			
Low pulse width	500 ns min			
Schmitt trigger hysteresis	0.76 V typ			
	0.4 V min			
	1.2 V max			
Input high voltage threshold	1.74 V typ			
	1.3 V min			
	2.2 V max			
Input high voltage limit	5.5 V absolute max			
Input low voltage threshold	0.98 V typ			
	0.6 V min			
	1.5 V max			
Input low voltage limit	−0.5 V absolute min			
	0 V recommended min			

Memory

Table 15. Memory specifications

Parameter	Specification	
FIFO	12K (12,288) samples	
Non-volatile EEPROM	2,048 bytes (768 bytes calibration, 256 bytes user, 1,024 bytes firmware use)	

Microcontroller

Table 16. Microcontroller specifications

Parameter	Specification	
Туре	High performance 16-bit RISC microcontroller	

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603-746-5524

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Power

Table 17. Power specifications

Parameter	Condition	Specification	
Supply current, USB source	During enumeration	< 100 mA	
	After USB enumeration or connected to USB charger / supply	< 500 mA	
Battery power		Two AA cells	
		Alkaline, NiCd, and NiMH cells supported	
Battery charging		NiMH and NiCd charging supported.	
		Alkaline cells automatically detected and not	
		charged.	
+VO power available	After USB enumeration or	3.3 V nominal	
	Bluetooth connection		
+VO output current	After USB enumeration or	50 mA max	
-	Bluetooth connection		

Note 9: When operating from batteries there is a user configurable power-off timer that will turn the device off when there is no host connection for the specified amount of time. The timer can be disabled or set to a value from 1-255 minutes.

Bluetooth

Table 18. Bluetooth specifications

Parameter Specification		
Device type	Bluetooth 2.1	
Device compatibility	Backwards compatible with Bluetooth 2.0, 1.2, and 1.1	
Bluetooth profile	Serial Port Profile (SPP)	

Note 10: The Bluetooth radio is disabled when the device is connected to a USB host.

USB

Table 19. USB specifications

Parameter	Specification		
Device type	USB 2.0 full speed		
Device compatibility	USB 1.1, USB 2.0		

Environmental

Table 20. Environmental specifications

Parameter	Specification
Operating temperature range	0 °C to 50 °C
Storage temperature range	–40 °C to 70 °C
Humidity	0% to 90% non-condensing

Mechanical

Table 21. Mechanical specifications

Parameter	Specification
Dimensions $(L \times W \times H)$	146.56 × 81.31 × 27.18 mm (5.77 × 3.28 × 1.07 in.)
USB cable length	3 m (9.84 ft) max

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User connection length	3 m (9.84 ft) max
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Signal connector

Table 22. Screw terminal specifications

Parameter	Specification
Connector type	Screw terminal
Wire gauge range 16 AWG to 30 AWG	

Screw terminal pinout

Differential mode pinout

Table 23. Screw terminal pinout

Pin	Signal name	Pin description	Pin	Signal name	Pin description
1	CH0H	Analog input 0 HI	17	DIO0	Digital I/O bit 0
2	CH0L	Analog input 0 LO	18	DIO1	Digital I/O bit 1
3	AGND	Analog ground	19	DIO2	Digital I/O bit 2
4	CH1H	Analog input 1 HI	20	DIO3	Digital I/O bit 3
5	CH1L	Analog input 1 LO	21	DIO4	Digital I/O bit 4
6	AGND	Analog ground	22	DIO5	Digital I/O bit 5
7	CH2H	Analog input 2 HI	23	DIO6	Digital I/O bit 6
8	CH2L	Analog input 2 LO	24	DIO7	Digital I/O bit 7
9	AGND	Analog ground	25	GND	Digital ground
10	СНЗН	Analog input 3 HI	26	+VO	User voltage output
11	CH3L	Analog input 3 LO	27	GND	Digital ground
12	AGND	Analog ground	28	GND	Digital ground
13	AOUT0	Analog output 0	29	AICKI	External pacer clock input
14	AGND	Analog ground	30	CTR	Counter input
15	AOUT1	Analog output 1	31	TRIG	Digital trigger input
16	AGND	Analog ground	32	GND	Digital ground

Single-ended mode pinout

Table 24. Screw terminal pinout

Pin	Signal name	Pin description	Pin	Signal name	Pin description
1	CH0H	Analog input 0	17	DIO0	Digital I/O bit 0
2	CH0L	Analog input 1	18	DIO1	Digital I/O bit 1
3	AGND	Analog ground	19	DIO2	Digital I/O bit 2
4	CH1H	Analog input 2	20	DIO3	Digital I/O bit 3
5	CH1L	Analog input 3	21	DIO4	Digital I/O bit 4
6	AGND	Analog ground	22	DIO5	Digital I/O bit 5
7	CH2H	Analog input 4	23	DIO6	Digital I/O bit 6
8	CH2L	Analog input 5	24	DIO7	Digital I/O bit 7
9	AGND	Analog ground	25	GND	Digital ground
10	СНЗН	Analog input 6	26	+VO	User voltage output
11	CH3L	Analog input 7	27	GND	Digital ground
12	AGND	Analog ground	28	GND	Digital ground
13	AOUT0	Analog output 0	29	AICKI	External pacer clock input
14	AGND	Analog ground	30	CTR	Counter input
15	AOUT1	Analog output 1	31	TRIG	Digital trigger input
16	AGND	Analog ground	32	GND	Digital ground

CE Declaration of Conformity

Manufacturer: Measurement Computing Corporation

Address: 10 Commerce Way

Suite 1008

Norton, MA 02766

USA

Category: Electrical equipment for measurement, control and laboratory use.

Date of Issue: June 24, 2013

Measurement Computing Corporation declares under sole responsibility that the product

BTH-1208LS

to which this declaration relates is in conformity with the relevant provisions of the following standards or other documents:

- EMC Directive 2004/108/EC: General Requirements, EN 61326-1:2006 (IEC 61326-1:2005)
- The Radio and Telecommunications Terminal Equipment (R&TTE) Directive 1999/5/EC
- EMC Standard for Radio Equipment and Services EN 301-489-1 / EN 301-489-17
- EMC Standard for Wideband Transmission Systems EN 300-328
- Essential Health and Safety Requirement of the Low Voltage Directive 2006/95/EC

Emissions:

- EN 55011 (2009) + A1:2010/ CISPR 11(2009) + A1:2010: Radiated emissions: Group 1, Class A
- EN 55011 (2009) + A1:2010/ CISPR 11(2009) + A1:2010: Cond. emissions: Group 1, Class A
- EN 61000-3-2 (2006) + A2:2009: Harmonic Current Emissions, Class A
- EN 61000-3-3 (2008): Voltage Fluctuations and Flicker in Low Voltage, Class A

Immunity: EN 61326-1:2006, Table 3.

- IEC 61000-4-2 (2008): Electrostatic Discharge immunity.
- IEC 61000-4-3 (2010): Radiated Electromagnetic Field immunity.
- IEC 61000-4-4 (2012): Electric Fast Transient Burst Immunity.
- IEC 61000-4-5 (2005): Surge Immunity.
- IEC 61000-4-6 (2008): Radio Frequency Common Mode Immunity.
- IEC 61000-4-11 (2004): Voltage Interrupts.

Supplementary Information:

- This product meets the EMC requirements of the United States (FCC Part 15, Class A), Canada (ICES-001, Group 1, Class A), and Australia/New Zealand (AS/NZS CISPR 11, Group 1, Class A).
- This product meets IEC61010-1, UL 61010-1, and CSA 61010-1 safety standards.

To maintain compliance to the standards of this declaration, the following conditions must be met.

- The host computer, peripheral equipment, power sources, and expansion hardware must be CE compliant.
- All I/O cables must be shielded, with the shields connected to ground.
- I/O cables must be less than 3 meters (9.75 feet) in length.
- The host computer must be properly grounded.
- Equipment must be operated in a controlled electromagnetic environment as defined by Standards EN 61326-1:2006, or IEC 61326-1:2005.

Declaration of Conformity based on tests conducted by Chomerics Test Services, Woburn, MA 01801, USA in June, 2013. Test records are outlined in Chomerics Test Reports #EMI6320A.13and #TR6320B.13.

We hereby declare that the equipment specified conforms to the above European Community Directives and Standards.

Carl Haapaoja, Director of Quality Assurance

Call Jayray

Measurement Computing Corporation 10 Commerce Way Suite 1008 Norton, Massachusetts 02766

(508) 946-5100 Fax: (508) 946-9500

E-mail: info@mccdaq.com

www.mccdaq.com